

GF4000

Gas Flow Sensor

Analog and Digital(I2C) Output

Datasheet

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Document Revision History

Revision	Description	Date
V 1.0	Initial version	2020.11.03
V 1.1	Revise parameter, protocol	2020.12.26
V 1.2	Revise curve, parameter	2021.01.08
V 1.3	Revise parameter	2023.01.09
V 1.4	Add custom version	2024.06.13
V 1.5	Add temperature definition	2024.10.08

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1. Product Description

1.1 Product Features

- State-of-the-art MEMS technology
- High sensitivity, Wide measurement range
- High precision, High resolution
- Reliable performance
- Fast response optional
- Bidirectional air flow optional
- Analog or digital output optional



1.2 Application Areas

- Portable ventilator, small home oxygen concentrator
- Continuous Positive Airway Pressure (CPAP) device
- Anesthesia for childbirth
- Critical care equipment
- Air purifier
- Environmental climate monitoring
- Fuel cell control
- HVAC (Heating, Ventilation, and Air Conditioning)

2. Function Description

The GF4000 series measures the small gas flow rate from 0 to 500SLM based on thermodynamic principles. It can measure dry air, nitrogen and other non-corrosive gas with high precision. It contains a MEMS thermal sensor chip and a high-performance CMOS microprocessor. Combined with a unique calibration scheme, It can output real-time and accurate flow signals.

2.1 Electrical Characteristics

Power supply: (8~24) VDC ,The default value: 12 ± 0.1 VDC

Reference Temperature: 25°C, Relative Humidity: 40% ~ 60 % RH

Parameter		Min.	Typ.	Max.	Unit
Optional Flow Range		-		4000	
Accuracy	$\leq 1000\text{SLM}^{①}$	-	-	± 1.5	%FS
	$> 1000\text{SLM} \& \leq 2000\text{SLM}^{①}$	-	-	± 2.5	%FS
	$> 2000\text{SLM} \& \leq 5000\text{SLM}^{①}$	-	-	± 3.5	%FS
Offset Drift		-	0.2	-	%FS
Resolution		-	0.1	-	%FS
Analog output voltage ^②		0.5		4.5	V
SCL clock frequency ^③			-	100	KHz
low-level input voltage ^③		-	-	0.5	V
High-level input voltage ^③		4	-	-	V
Low-level output voltage ^③		-	-	0.5	V
High-level output voltage ^④		4	-	-	V
Operating voltage	Standard Version	8	12	24	V
	Low Power Supply	4.75	5	5.25	V
Operating current		5	15	30	mA
Response time ^⑤	Standard Version	-	20	-	mSec
	High Response	-	5	-	mSec
Work pressure		-	-	200	kPa
Compensation temperature		0	-	50	°C
Operating temperature		-10	-	60	°C
Storage temperature		-20	-	70	°C
Electrical interface		2.54 mm 5 Pin Dupont latch-spring connector			
Materials that flow gas contact		Silicon, FR4, PPS , Fibreglass, Epoxy resin			

Note:

- ① The range indicate the rated flow range of measured flow sensor.
- ② This specification is for analog output only. Contact Sencoch for custom voltage.
- ③ This specification is for digital output only.
- ④ The SDA/SCL of the product is internally pulled up to the power supply, so no external pull-up resistor is required.

The range is 0– (5–500 SLM) and can be customized.

- ⑤ Different response times correspond to different output stability, please select according to actual requirement

2.2 External Structure (Tolerance/ Unit: $\pm 0.3\text{mm}$)

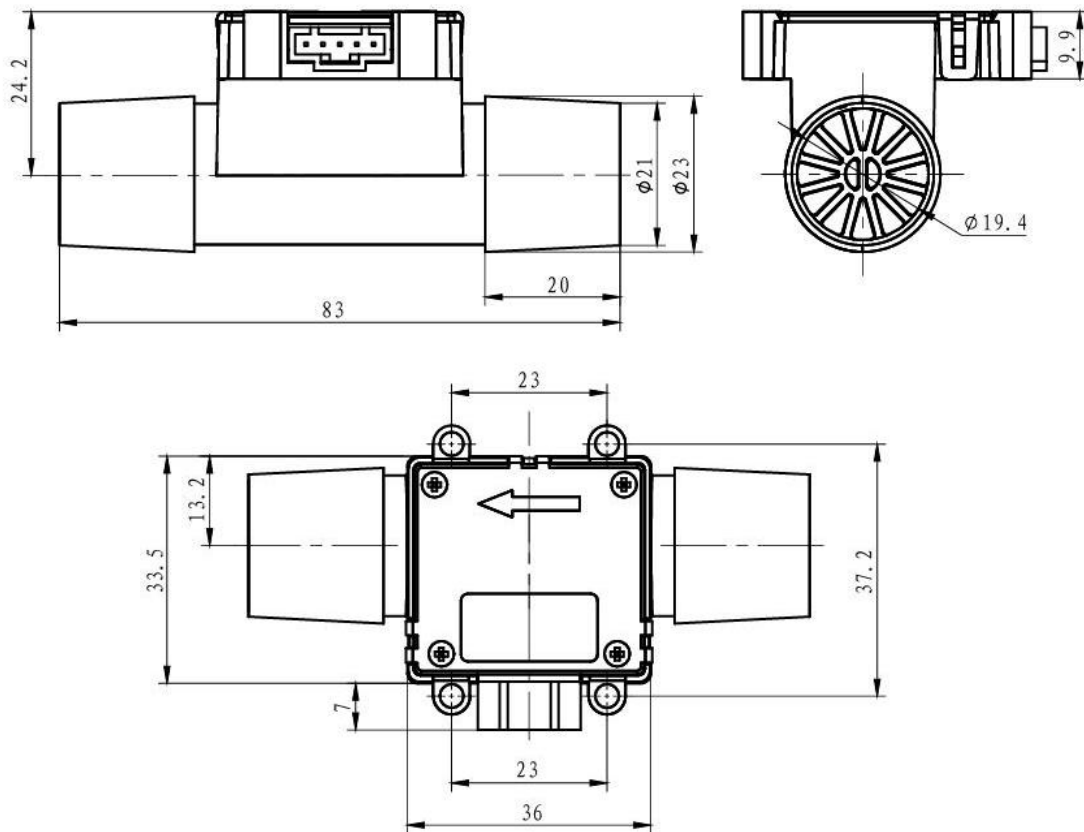


Fig.1 Sensor dimensions

2.3 Electrical Connections

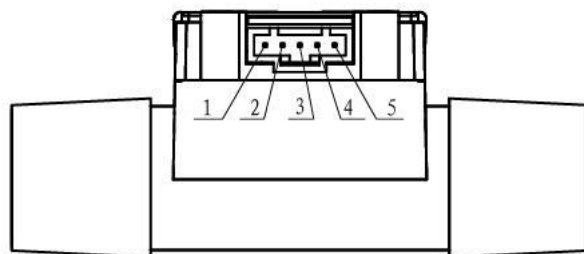


Fig.2 2.54mm 5 Pin Jumper latch spring connector

Pin Definitions for Analog output

Serial Number	Description	Remark
1	VOUT	Product output voltage signal
2	VDD	Power supply input positive
3	GND	Power supply input negative
4	NC	No connect
5	NC	No connect

Pin Definitions for I2C Interface

Serial Number	Description	Remark
1	NC	No connect
2	VDD	Power supply input positive
3	GND	Power supply input negative
4	SCL	I2C clock signal
5	SDA	I2C data port

※※※ This product has no reverse polarity protection, please pay attention to the power polarity during assembly.

3. Order Guide

GF 4 200 F -L- B- A0545 A WX

GF	Product Category Flow sensor
4XXX	Product Series 4000 Series
200	Range 200: 200SLM;
F(Optional)	High response version; Default Standard version
L(Optional)	5V Power supply voltage; Default 8-24V
B	B: Bidirectional version; Default 8-24V
A0545	Output A0545: 0.5~4.5V or A1050: 1.0 ~5.0V; D: I2C interface
A	Gas Type A: Air; N: Nitrogen; O: Oxygen; C: Carbon dioxide
WX	Company interior code

4. Routine Measuring Ranges

Model	Flow range (SLM)
GF4005	0-5
GF4012	0-12
GF4020	0-20
GF4035	0-35
GF4050	0-50
GF4100	0-100
GF4150	0-150
GF4200	0-200
GF4300	0-300
GF4450	0-450
GF4500	0-500

Note: SLM: Standard liters per minute. Standard conditions. 0°C, 101.325 kPa.

5. Flow Rate Calculation Formula

Analog output:

GF4200-A0545(Unidirectional)

Flow rate = $[(V_{out} - 0.5 \text{ V})/4 \text{ V}] \times \text{full scale flow rate}$

For example: GF4200-A-A, when reading the output voltage of 2.5V,

The Instantaneous flow rate is $[(2.5\text{V} - 0.5\text{V})/4\text{V} \times 200 \text{ SLM}] = 100 \text{ SLM}$

GF4200-B-A0545(Bidirectional)

Flow rate = $[(V_{out} - 0.5 \text{ V})/2 \text{ V}] \times \text{full scale flow rate}$

For example: GF4200-B-A0545-A, when reading the output voltage of 1.0V,

The Instantaneous flow rate is $[(1.0\text{V} - 2.5\text{V})/2\text{V} \times 200 \text{ SLM}] = -150 \text{ SLM}$

Digital Output

GF4150-D(Unidirectional)

Flow rate = $[\text{I2C output reading}]/\text{proportionality factor K}$

Example: GF4150-D-A, when reading output 11055

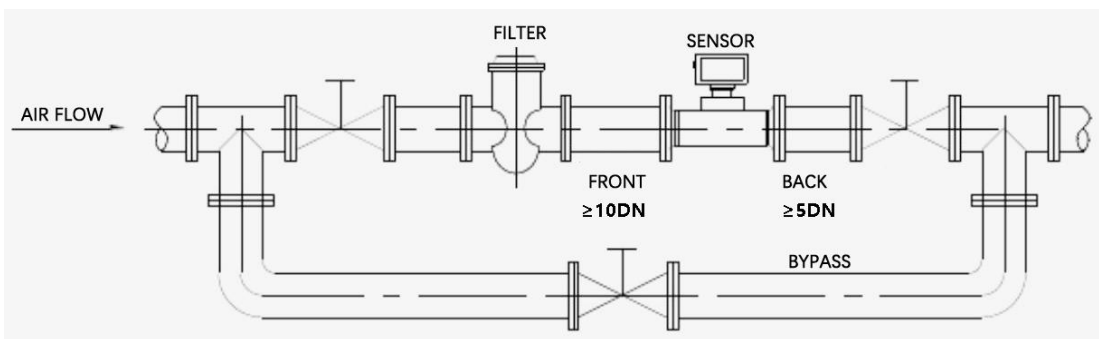
Instantaneous flow rate is $[11055]/10 = 110.55 \text{ SLM}$

Unidirectional Version		Bidirectional version	
K Full Scale Range	K	K Full Scale Range	K
$5\text{SLM} \leq \text{flow rate} < 50\text{SLM}$	1000	$5\text{SLM} \leq \text{flow rate} < 30\text{SLM}$	1000
$50\text{SLM} \leq \text{flow rate} \leq 300\text{SLM}$	100	$30\text{SLM} \leq \text{flow rate} \leq 300\text{SLM}$	100
$300\text{SLM} \leq \text{flow rate} \leq 500\text{SLM}$	10	$300\text{SLM} \leq \text{flow rate} \leq 500\text{SLM}$	10

6. Precautions for Use

6.1 Recommended installation instructions

GF 4000 Series Installation, the recommended pipe length is 10 parts at the front and 5 parts at the back. That is, the length of the inlet pipe is ten times the diameter of the product. The length of output pipe is five times the diameter; the products are installed concentrically; Air flow direction need be consistent with product indication direction; product pin connections must correspond to product pin definitions. After confirming that everything is correct, power on and it will work. See the diagram below:



6.2 Precautions for use

- 1) The product can only be used normally in the environment defined in this specification;
- 2) Pay attention to the gas flow direction indicator during installation. Connection and leak detection should be carried out in accordance with the relevant procedures;
- 3) During product use, it is prohibited to simultaneously install pipes, clean pipes, or perform other improper operations that introduce large amounts of impurities, as this may damage the product.
- 4) If the gaseous medium contains water vapor Impurities may cause a decrease or damage to the sensor 's sensitivity.
- 5) Pay attention to the positive and negative terminals of the power supply. If the positive and negative terminals of the power supply are reversed This will cause the internal circuitry of the sensor to burn out. This affects the normal use of the product.

- Please confirm under actual usage conditions.

Since this specification is for a single product, please verify the performance and quality under actual use to improve reliability.

6.3 Safety Precautions

This product is used in general electronic devices (communication equipment) Measuring equipment (Work machinery, etc.) It is made from semiconductor components. Products using these semiconductor components It may malfunction or fail due to external interference and surges. Therefore, please use it in practice. Verify performance and quality under test conditions. Just in case. Please incorporate safety features into the device (fuse). Circuit breakers and other protective electrical circuits Road layout (Multi-functional devices, etc.) Even if a misoperation occurs, it will not endanger life, body and property, etc. To prevent injury and the occurrence of the accident Please be sure to comply with the following:

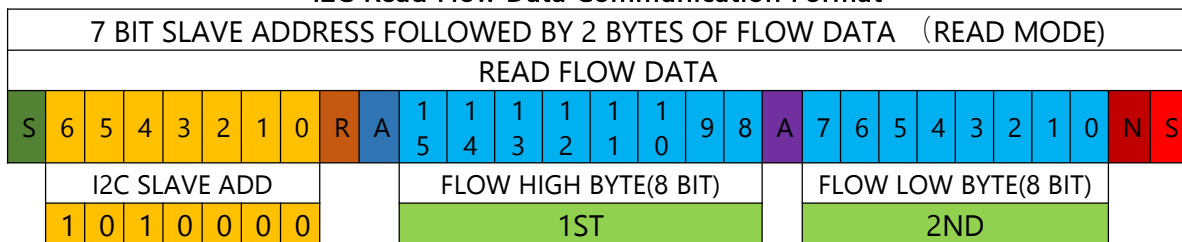
- (1) The drive current and voltage should be used below the rated values ;
- (2) Please wire according to the electrical definitions. Especially after reversing the power supply connection. It may be due to fever, smoke accidents caused by circuit damage such as fire, therefore please take note;
- (3) Please be careful when securing the product and connecting the pressure inlet.

7. I2C Communication Protocol

The I2C protocol is a standardized protocol for exchanging information between integrated circuits or functional units; The I2C bus uses a single data line (SDA), add a clock line (SCL) to complete data transmission and expand peripheral devices. There are three data transmission methods on the I2C bus. Transmission speed: Standard mode, Fast mode, and High-speed mode. Standard mode is 100 Kbps, and Fast mode is 400 Kbps. (This sensor only supports standard mode transmission speeds.) Addressing of each node is done via soft addressing, saving chip select lines; the standard addressing byte SLAM is 7 bits. It can address 127 units.

The default address for I2C is 0x32.

I2C Read Flow Data Communication Format



- **S**: START Condition
- **6**: SLAVE Address Bit
- **R**: READ Bit(Read=1)
- **A**: ACK from SLAVE
- **15**: Date Bit
- **A**: ACK from Master
- **N**: NACK from Master
- **S**: STOP Condition

The flow data is divided into 2 bytes, the first byte is the high byte of the flow data, the second byte is the low byte of the flow data, the flow data is K (see airflow calculation formula) times the actual flow rate. The default unit of flow data is L/M (Liter/Minute), for example, when K=100, read the hexadecimal data as 03E8. Then it is converted to decimal system. The current actual flow rate is 10.00 L/M. If the required flow unit is M3/H (cubic meters per hour), then the following formula can be used to calculate: $M = L / 1000 * 60$. Calculating gives a flow rate of 0.6 M3/H

Example: Standard program for reading flow sensor via digital output

```
//Read the flow sensor module routine

// SDA,SCL correspond to the respective I/O pins of the microcontroller.

//host sends 0 xA 1 Give to slave machine from the machine back 2 Byte data to host

#include " IIC_Master.h
"      #define   SDA PA 0
#define SCL PA1
Unsigned int IIC_RX_Buf[2];
bit ErrorBit;
void I2C_Init(void)
{
    SDA _ INPUT =0; //Program initialization, the
    SDA pin is set to output
    SCL INPUT. =0; // Program initialization sets the
    SCL pin as an output.  SDA=1;
    SCL=1;
}
Void I2C_Start (void)
{
    SDA=1;
    Delay_Us(20);
    SCL=1;
    Delay_Us(20);
    SDA=0;
    Delay_Us(20);
    SCL=0;
    Delay_Us(20);
}

//-----
void I2C_Stop(void)
{
    SCL=0;
    Delay_Us(20);
    SDA=0;
    Delay_Us(20);
```

```
SCL =1;
Delay_Us(20);
SDA =1;
Delay_Us(20);
}
//-----
-
void I2C_ACK(void)
{
    SDA =0;
    Delay_Us(20);
    SCL =1;
    Delay_Us(20);
    SCL =0;
    Delay_Us(20);
}
//-----
-
void I2C_NoAck(void)
{
    SDA =1;
    Delay_Us(20);
    SCL =1;
    Delay_Us(20);
    SCL =0;
    Delay_Us(20);
}
//-----
-
Unsigned int I2C_ReadByte ( void ) {
    Unsigned int ucValue =0;
    Unsigned int ucIndex;

    SDA =1;
    Delay_Us (20);
    SDA _ INPUT =1; // Set the SDA pin as input
```

```
Delay_Us(20);
for ( ucIndex = 0; ucIndex < 8; ucIndex++ )
{
    ucValue < <= 1;
    SCL=0;
    Delay_Us(20);
    SCL=1;
    Delay _ Us (20);
    if (IIC_DAT) ==1) // IIC _ DAT That is, SDA is set as input, Read SDA pin
    level
    {ucValue = ucValue |0x01;}
    else
    {ucValue = ucValue & 0 xfe
    ;} Delay _ Us (20);
    SCL=0;
    Delay _ Us (20); }
    SDA _ INPUT =0; // will SDA is set to
    output Delay _ Us (20);
    return
    ucValue;}
//-----
void I2C_WriteByte (unsigned int ucData )
{
    u8 i;
    for (i = 0; i < 8; i + + )
    {
        SCL=0;
        Delay_Us(20);
        If ((ucData & 0x80) == 0x80)
        {
            SDA=1;
            Delay_Us(20);
        }
        else
        {
            SDA=0;
            Delay_Us(20);
        }
    }
}
```

```
}

    SCL=1;
    Delay_Us(20);

    SCL=0;
    Delay_Us(20);
    ucData < <= 1;

}
SCL=1;
Delay_Us(20);
ErrorBit = IIC_DAT;
Delay_Us(20);
SCL=0;
Delay_Us(20);
}

void iic_master_proc(void)
{
    Unsigned int count=2, i;
    I2C_Init() ;
    I2C_Start();
    I2C_WriteByte (0 xa 1); //Write address 0 xA 1
    for(i = 0;i < count;i++)
    {
        IIC_RX_Buf[i] = I2C_ReadByte();
        if(i < (count -1)) I2C_ACK();
        else                I2C_NoAck();
    }
    I2C_Stop();
}
```